

LECTURE 16

CGS, MGS, Householder triangulation

end class early for alphabetizing situation

Q Write down definitions for the following

① Orthonormal basis $\{b_1, \dots, b_n\}$

② Orthogonal matrix Q

③ Orthogonal projector P

eg. " P is an orthogonal projector iff _____ "

④ Normalization

Recall we described Gauss Elim \leftrightarrow LU decomposition.

Goal: QR decomp as result of same algorithm.

Historical / intellectual steps:

alg for
computing
QR.

- ① Classical Gram-Schmidt (CGS)
- ② Modified Gram-Schmidt (MGS) - better (why?)
- ③ Householder triangulation (next time)

- Understand how these algorithms work
- the drawbacks/issues!
- how to implement most efficiently

CGS via orthogonal projectors

$$P^2 = P, \text{ range}(P) \perp \text{null}(P)$$

Setting $A \in \mathbb{R}^{m \times n}$, $n \leq m$, full rank

$\Rightarrow \{a_{.1}, \dots, a_{.n}\} = \{\vec{a}_1, \dots, \vec{a}_n\}$ are linearly indep

want: ON basis for \mathbb{R}^n from A .

$P_j =$ orth proj to orth. comp. $\langle q_1, \dots, q_{j-1} \rangle^\perp$

Algorithm

for $j = 1:n$

$$\begin{cases}
 v_j = a_j \\
 \text{for } i = 1:j-1 \\
 \begin{cases}
 r_{ij} = q_i^T a_j \\
 v_j = v_j - r_{ij} q_i
 \end{cases} \\
 r_{jj} = \|v_j\| \\
 q_j = v_j / r_{jj}
 \end{cases}$$

$$\begin{aligned}
 & j=1 \\
 & v_1 = a_1 \\
 & r_{11} = \|a_1\| \\
 & q_1 = \frac{a_1}{\|a_1\|}
 \end{aligned}$$

$$\begin{aligned}
 & j=2 \\
 & v_2 = a_2 \\
 & \text{for } i \in \{1\}: \\
 & r_{12} = q_1^T a_2 \\
 & v_2 = v_2 - r_{12} q_1 \\
 & r_{22} = \|v_2\| \\
 & q_2 = \frac{v_2}{r_{22}} = \frac{v_2}{\|v_2\|}
 \end{aligned}$$

$P_1 = I$
 $P_j =$ orth. proj onto orth complement $\langle q_1, \dots, q_{j-1} \rangle^\perp$
 $P_2 a_2 = v_2$ (store)

each $q_j \perp \underbrace{\langle q_1, \dots, q_{j-1} \rangle}_{\hat{Q}_{j-1}}$

$P_j = I - \hat{Q}_{j-1} \hat{Q}_{j-1}^T$ projects onto orth complement $\langle q_1, \dots, q_{j-1} \rangle^\perp$

Remark. Note the r_{ij} are computed columnwise.

$$\begin{bmatrix}
 \textcircled{1} r_{11} & \textcircled{2} r_{12} & \textcircled{3} r_{13} & \textcircled{4} r_{14} \\
 & r_{22} & r_{23} & r_{24} \\
 & & r_{33} & r_{34} \\
 & & & r_{44}
 \end{bmatrix} = R$$

Issues

- lots of calculations in inner for loop; numerical errors compound...
- rank $P_j = m - (j-1)$. Projecting onto small dimension is dangerous - matters a lot if you have error in that direction.

* Unstable for high dimensions!

(HWdb - you'll do an example)

MGS

Idea Instead of $P_j = \text{proj onto orth complement at each step}$, we use a composition of all the rank $m-1$ projectors

$$P_j = (P_{\perp q_{j-1}})(P_{\perp q_{j-2}}) \dots (P_{\perp q_1})$$

$\uparrow = I - q_i q_i^T$

(and $P_1 = I$ still)

Observe that if there were no error, mathematically we're doing exactly the same process; orth. proj onto the same subspace.

But the seqn of arith operations differs:

Algorithm

for $i = 1:n$

$$v_i = a_i$$

for $i = 1:n$

$$\left\{ \begin{array}{l} r_{ii} = \|v_i\| \\ q_i = v_i / r_{ii} \quad \text{normalize first.} \\ \text{for } j = i+1:n \quad \{q_1, \dots, q_i\} \text{ already done} \\ \left\{ \begin{array}{l} r_{ij} = q_i^T v_j \\ v_j = v_j - r_{ij} q_i \end{array} \right. \end{array} \right.$$

remove components in the q_1, \dots, q_i directions.

for all remaining vectors (earlier than for CGS).

Rank. Order of computation of the r_{ij} :

