# MAT180 HW06 

Solutions

Due 5/12/23 at 11:59 pm on Gradescope

Reminder. Your homework submission must be typed up in full sentences, with proper mathematical formatting.

## Exercise 1

Below is a depiction of the Stevedore knot $6_{1}$, drawn as the boundary of an oriented Seifert surface built out of one disk and two twisted bands:

(a) Let $\gamma_{1}$ be the counter-clockwise loop that goes through the left band (only, exactly once), and let $\gamma_{2}$ be the counter-clockwise loop going through the right band (only, exactly once). Sketch a diagram of the surface $F$, the curves $\gamma_{1}, \gamma_{2}$, and their pushoffs $\gamma_{1}^{+}, \gamma_{2}^{+}$.
(b) Construct the Seifert matrix $V$ for this surface.
(c) Compute $\operatorname{det}\left(V-t V^{\top}\right)$; then, if needed, multiply it by $t^{n}$ for some $n \in \mathbb{Z}$ (possibly negative) so that the powers of $t$ appearing in the Alexander polynomial of $6_{1}$ are balanced around 0 .

Solution.
(a) See Figure 1.
(b) Using Figure 1, we compute the following linking numbers:

$$
\begin{array}{lc}
\operatorname{lk}\left(\gamma_{1}, \gamma_{1}^{+}\right)=-1 & \operatorname{lk}\left(\gamma_{1}, \gamma_{2}^{+}\right)=0 \\
\operatorname{lk}\left(\gamma_{2}, \gamma_{1}^{+}\right)=-1 & \operatorname{lk}\left(\gamma_{2}, \gamma_{2}^{+}\right)=+2
\end{array}
$$



Figure 1: A choice of basis $\left\{\gamma_{1}, \gamma_{2}\right\}$ for $H_{1}(F)$, where $F$ is the Seifert surface for $6_{1}$ in Exercise 1.

The Seifert matrix for $\left(F,\left\{\gamma_{1}, \gamma_{2}\right\}\right)$ is

$$
V=\left[\begin{array}{ll}
-1 & 0 \\
-1 & 2
\end{array}\right] .
$$

(c) We compute

$$
\begin{aligned}
\operatorname{det}\left(V-t V^{\top}\right)= & \operatorname{det}\left(\left[\begin{array}{ll}
-1 & 0 \\
-1 & 2
\end{array}\right]-t\left[\begin{array}{cc}
-1 & -1 \\
0 & 2
\end{array}\right]\right)=\operatorname{det}\left(\left[\begin{array}{cc}
-1+t & t \\
-1 & 2-2 t
\end{array}\right]\right) \\
& =(-1+t)(2-2 t)+t=-2 t^{2}+5 t-2,
\end{aligned}
$$

which, up to an integer power of $t$, is equivalent to $\Delta_{K}(t)=-2 t+5-2 t^{-1}$, where $K=6_{1}$.

## Exercise 2

Consider the usual diagram of the Figure 8 in the Rolfsen knot table.
(a) Draw the Seifert surface $F$ resulting from Seifert's algorithm such that 'most' of the surface is facing upward (i.e. you see more of the positive side of $F$ than the negative side). Since there are four crossings, you should have four bands connecting the Seifert disks.
(b) The surface $F$ is homotopy equivalent to a graph with four edges. Draw this graph $\Gamma$. Then, contract edges until you have a graph $\Gamma_{*}$ with only one vertex; draw this process as a sequence of graphs ending with $\Gamma_{*}$.
(c) Using your $\Gamma_{*}$, choose a basis $\left\{\gamma_{i}\right\}$ for the first homology $H_{1}(F)$ of $F$. (Remember to orient your curves!) Draw these curves on a copy of your surface $F$; be careful near the crossings! Draw push-offs $\left\{\gamma_{i}^{+}\right\}$in a different color.
(d) Compute the Seifert matrix $V$ with respect to the data $\left(F,\left\{\gamma_{i}\right\}\right)$ that you've chosen.
(e) Compute $\operatorname{det}\left(V-t V^{\top}\right)$ and compare this with the Alexander polynomial of the Figure 8 knot.

## Solution.

(a) See Figure 2.


Figure 2: A Seifert surface $G$ for $J=4_{1}$ obtained from Seifert's algorithm, along with a choice of basis $\left\{\gamma_{1}, \gamma_{2}\right\}$ for $H_{1}(G)$.
(b) See Figure 3.


Figure 3: On the left, the graph $\Gamma$ where vertices are given by the Seifert disks for the surface $G$, and edges are given by the attached bands corresponding the crossings of the diagram of $J$. On the right, a homotopy equivalent graph with just one vertex, and a choice of orientation on the remaining loops.
(c) See Figures 2 and 3.
(d) Using my choice of $\left(G,\left\{\gamma_{1}, \gamma_{2}\right\}\right)$, the Seifert matrix is

$$
V=\left[\begin{array}{cc}
-1 & +1 \\
0 & +1
\end{array}\right]
$$

(e) We compute:

$$
\begin{gathered}
\operatorname{det}\left(V-t V^{\top}\right)=\left[\begin{array}{cc}
-1 & 1 \\
0 & 1
\end{array}\right]-t\left[\begin{array}{cc}
-1 & 0 \\
1 & 1
\end{array}\right]=\left[\begin{array}{cc}
-1+t & 1 \\
-t & 1-t
\end{array}\right] \\
=(-1+t)(1-t)+t=-t^{2}+3 t-1
\end{gathered}
$$

which is equivalent (up to a power of $t$ ) to $\Delta_{J}(t)=-t+3-t^{-1}$.

## Exercise 3

Let $V$ be a matrix corresponding to some data $\left(F,\left\{\gamma_{i}\right\}_{i=1}^{2 g}\right)$, where $g=g_{3}(F)$. Let $\tilde{F}$ be a stabilization of $F$, and let $\widetilde{V}$ be the Seifert matrix computed from the data $\left(\tilde{F},\left\{\gamma_{i}\right\} \cup\left\{\tilde{\gamma}_{1}, \tilde{\gamma}_{2}\right\}\right)$, where

$$
\operatorname{lk}\left(\tilde{\gamma}_{1}, \tilde{\gamma}_{1}^{+}\right)=\operatorname{lk}\left(\tilde{\gamma}_{2}, \tilde{\gamma}_{1}^{+}\right)=\operatorname{lk}\left(\tilde{\gamma}_{2}, \tilde{\gamma}_{2}^{+}\right)=0 \quad \text { and } \quad \operatorname{lk}\left(\tilde{\gamma}_{1}, \tilde{\gamma}_{2}^{+}\right)=1
$$

Therefore $\tilde{V}$ must have the following form:

$$
\widetilde{V}=\left(\begin{array}{c|cc}
V & U \\
\hline L & 0 & 1 \\
& 0 & 0
\end{array}\right),
$$

where $U \in \mathbb{R}^{2 g \times 2}$ and $L \in \mathbb{R}^{2 \times 2 g}$.
We want to understand how $\operatorname{det}(\widetilde{V}-t \widetilde{V})$ is related to $\operatorname{det}(V-t V)$. This is somewhat difficult in general. However, if we consider the special case where $U=L^{\top}=0 \in \mathbb{R}^{2 g \times 2}$ (as in the example drawn in class), then

$$
\widetilde{V}=\left(\begin{array}{c|c}
V & 0 \\
\hline 0 & 0 \\
\hline & 0
\end{array}\right)
$$

In this case, it is not difficult to compute $\operatorname{det}\left(\widetilde{V}-t \widetilde{V}^{\top}\right)$, by following the steps below.
(a) Write down the matrix $\widetilde{V}-t \widetilde{V}^{\top}$ in terms of $V$.
(b) Let $D$ denote the bottom right $2 \times 2$ block of the matrix $\widetilde{V}-t \widetilde{V}^{\top}$. Prove that $D$ is invertible, i.e. its determinant is a nonzero Laurent polynomial (a polynomial in negative, 0 , and positive powers of the variable $t$ ). Then, find the matrix inverse of $D$.
(c) Compute the Alexander polynomial $\operatorname{det}\left(\widetilde{V}-t \widetilde{V}^{\top}\right)$ by using the following fact from linear algebra, in terms of the polynomial $\operatorname{det}\left(V-t V^{\top}\right)$.

Fact. If $\left[\begin{array}{cc}A & B \\ C & D\end{array}\right]$ is a block matrix where $D$ is invertible, then

$$
\operatorname{det}\left(\left[\begin{array}{ll}
A & B \\
C & D
\end{array}\right]\right)=\operatorname{det}(D) \operatorname{det}\left(A-B D^{-1} C\right)
$$

Solution.
(a)

$$
\widetilde{V}-t \widetilde{V}^{\top}=\left(\begin{array}{c|cc}
V-t V^{\top} & 0 \\
\hline 0 & 0 & 1 \\
-t & 0
\end{array}\right) .
$$

(b) The determinant of $D=\begin{array}{cl}0 & 1 \\ -t & 0\end{array}$ is $t$, which is nonzero.
(c) In this case, $B, C=0$, so

$$
\operatorname{det}\left(\widetilde{V}-t \widetilde{V}^{\top}\right)=\operatorname{det}(D) \operatorname{det}(A)=t \cdot \operatorname{det}\left(V-t V^{\top}\right)
$$

Therefore, up to an overall power of $t, \operatorname{det}\left(\widetilde{V}-t \widetilde{V}^{\top}\right)$ is equivalent to $\operatorname{det}\left(V-t V^{\top}\right)$, so the Alexander polynomials agree.

